# EEE 180 Signals & Systems Background Prof. Pang

#### **Real Number**

X - 5 = 0 => X = 5 $X^2 - 4 = 0 => X = \mp 2$ 

#### **Imaginary Number**

 $X^{2} + 4 = 0 => X^{2} = -4$ =>  $X = \mp 2j$ or  $X = \mp 2i$ 

#### **Complex Number**

#### 2 + 3 j => 2: real part, 3j: imaginary part

real part imaginary part a + bj

#### **Complex Number**

# 2 + 3 i => 2: real part, 3i : imaginary part real part imaginary part **a** + **b**i

a + bj + c + dj = (a + c) + (b + d)j

2 + 3j + 4 + 5j = (2 + 4) + (3 + 5)j= 6 + 8j

$$a + bj - (c + dj) = (a - c) + (b - d)j$$

$$(4 + 8j) - (2 + 3j) = (4 - 2) + (8 - 3)j$$
  
= 2 + 5j

$$i * i = i^2 = -1$$

(2 + 3 j ) \* (4 + 5 j )

= -7+22j

# Complex Conjugate: q = p\*

- The complex conjugate of a complex number is the number with an equal real part and an imaginary party equal in magnitude but opposite in sign.
- The complex conjugate of p = a + bj is: q = a bj.  $q = p^*$



$$(a + bj) * (a - bj)$$
  
= a \* a - a \* (bj) + bj \* a - bj \* bj  
= (a<sup>2</sup> - b<sup>2</sup> x (-1)) + 0 j  
= a<sup>2</sup> + b<sup>2</sup>  
(4 + 5j) \* (4 - 5j)  
= 4<sup>2</sup> + 5<sup>2</sup> = 16 + 25 = 41

## **Complex Conjugate**

• The complex conjugate of P = a + bj is:  $P^* = a - bj$ .

• 
$$P + P^* = (a + bj) + (a - bj) = 2a$$

• 
$$P P^* = (a + bj) (a - bj) = a^2 + b^2 = |P|^2$$

The magnitude of the complex number :
 | P | = square root of ( P P\* ) = square root of (a<sup>2</sup> + b<sup>2</sup>).

$$(4 + 5 j) * (4 - 5 j) = 4^{2} + 5^{2} = 16 + 25 = 41$$
  

$$(2 + 3 j) * (4 + 5 j) = -7 + 22 j$$
  

$$\frac{(2 + 3 j)}{(4 - 5 j)}$$
  

$$= \frac{(2 + 3 j) (4 + 5 j)}{(4 - 5 j) (4 + 5 j)}$$
  

$$= \frac{-7 + 22 j}{41} = \frac{-7}{41} + \frac{22}{41} j$$

#### cosine and sine wave



$$cos \theta = cos(-\theta)$$
  
 $sin \theta = -sin(-\theta)$ 

#### **Polar Coordinates**



#### **Polar Coordinates**



#### **Polar Coordinates**



#### **Euler Formula**

# $\mathbf{e}^{\mathbf{j}\theta} = \cos\theta + \sin\theta\mathbf{j}$

#### **Euler Formula**



#### **Complex Number Arithmetic**

Question: Suppose 
$$p = r e^{j\theta}$$
,  
determine  $p^n$  and  $p^{1/n}$ .

$$p^{n} = (\mathbf{r} \mathbf{e}^{j\theta})^{n} = r^{n} (\mathbf{e}^{j\theta})^{n} = r^{n} \mathbf{e}^{jn\theta}$$

$$P^{1/n} = (r e^{j\theta})^{1/n} = r^{1/n} (e^{j\theta})^{1/n} = r^{1/n} e^{j\theta/n}$$

Question: Suppose 
$$p = 8 e^{\pi/3 j}$$
,  
determine  $p^2$  and  $p^{1/3}$ .  
Solution:

$$p^{2} = (8 e^{\pi/3 j})^{2} = 8^{2}(e^{\pi/3 j})^{2} = 64 e^{2\pi/3 j}$$

$$p^{1/3} = (8 e^{\pi/3 j})^{1/3} = 8^{1/3} (e^{\pi/3 j})^{1/3} = 2 e^{\pi/9 j}$$

#### Sinusoids



$$f(t) = C \cos(\omega t + \varphi)$$
  
= C cos ( 2\pi F t + \varphi)  
$$= C \cos(\frac{2\pi}{T}t + \varphi)$$
  
$$T = \frac{1}{F}$$
  
$$\omega = 2 \pi F$$

$$C \sin(\omega t + \frac{\pi}{2}) = C \cos(\omega t)$$

#### Sinusoids



#### **Trignometric Identity**

 $b = -C \sin \theta$ 

$$C \cos (\omega_0 t + \theta) = C \cos \theta \cos \omega_0 t - C \sin \theta \sin \omega_0 t$$
$$= a \cos \omega_0 t + b \sin \omega_0 t$$
in which

 $a = C \cos \theta$ ,



Phasor addition of sinusoids.

$$C = \sqrt{a^2 + b^2}$$
$$\theta = \tan^{-1} \left(\frac{-b}{a}\right)$$

#### Addition of Sinusoids

# $a \cos \omega_0 t + b \sin \omega_0 t = C \cos (\omega_0 t + \theta)$

#### Euler's Formula

$$\cos \varphi = \frac{1}{2} \left( e^{j\varphi} + e^{-j\varphi} \right)$$
$$\sin \varphi = \frac{1}{2j} \left( e^{j\varphi} - e^{-j\varphi} \right)$$

$$e^{j\varphi} = \cos \varphi + j \sin \varphi$$
  
 $e^{-j\varphi} = \cos \varphi - j \sin \varphi$ 

#### **Monotonic Exponentials**

a > 0



Monotonic exponentials.

#### Determinant

det A = 
$$|A| = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

#### Determinant

$$A = \begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix}$$
  
$$det(A) = a_1 \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix}$$
  
$$= a_1(b_2c_3 - b_3c_2) - a_2(b_1c_3 - b_3c_1) + a_3(b_1c_2 - b_2c_1)$$

#### Sketching an Exponentially Varying Sinusoid



#### **Cramer's Rule for Equation Solver**

$$2x_1 + x_2 + x_3 = 3$$

$$x_1 + 3x_2 - x_3 = 7$$

 $x_1 + x_2 + x_3 = 1$ 

In matrix form these equations can be expressed as

 $\begin{bmatrix} 2 & 1 & 1 \\ 1 & 3 & -1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 7 \\ 1 \end{bmatrix}$ Here, Determinant  $|\mathbf{A}| = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 3 & -1 \\ 1 & 1 & 1 \end{bmatrix} = 4$ 

$x_1 = \frac{1}{ \mathbf{A} }$	3	1	1	
	7	3	-1	$=\frac{8}{4}=2$
	1	1	1	
$x_2 = \frac{1}{ \mathbf{A} }$	2	3	1	
	1	7	-1	$=\frac{4}{4}=1$
	1	1	1	
$x_3 = \frac{1}{ \mathbf{A} }$	2	1	3	
	1	3	7 =	$=\frac{-8}{4}=-2$
	1	1	1	

#### **Cramer's Rule for Equation Solver**



We denote the matrix on the left-hand side formed by the elements  $a_{ij}$  as **A**. The determinant of **A** is denoted by  $|\mathbf{A}|$ . If the determinant  $|\mathbf{A}|$  is not zero, the set of equations (B.29) has a unique solution given by Cramer's formula

$$x_k = \frac{|\mathbf{D}_k|}{|\mathbf{A}|} \qquad k = 1, 2, \dots, n \tag{B.31}$$

where  $|\mathbf{D}_k|$  is obtained by replacing the *k*th column of  $|\mathbf{A}|$  by the column on the right-hand side of Eq. (B.30) (with elements  $y_1, y_2, \ldots, y_n$ ).

#### Matrix Transpose

$$\mathbf{A} = \begin{bmatrix} 2 & 1 \\ 3 & 2 \\ 1 & 3 \end{bmatrix} \quad \text{then} \quad \mathbf{A}^T = \begin{bmatrix} 2 & 3 & 1 \\ 1 & 2 & 3 \end{bmatrix}$$

$$\mathbf{A} = (a_{ij})_{m \times n}$$

$$\mathbf{A}^T = (a_{ji})_{n \times m}$$

Switch the row elements of the original matrix to get the column elements of the transposed matrix.

 $(\mathbf{A}^T)^T = \mathbf{A}$ 

#### Matrix Addition

$$\mathbf{G} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 6 & 7 \end{bmatrix}, \quad \mathbf{F} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$\mathbf{F} + \mathbf{G} = \begin{bmatrix} \mathbf{O} & 2 \\ 3 & 4 \\ \mathbf{O} & 7 \end{bmatrix} + \begin{bmatrix} \mathbf{O} & 0 \\ 1 & 1 \\ \mathbf{O} & 1 \end{bmatrix} = \begin{bmatrix} \mathbf{+} & 2 + 0 \\ 3 + 1 & 4 + 1 \\ \mathbf{0} + \mathbf{O} & 7 + 1 \end{bmatrix} = \begin{bmatrix} \mathbf{O} & 2 \\ \mathbf{O} & 2 \\ \mathbf{O} & 4 \\ \mathbf{O} & 5 \\ \mathbf{O} & 7 \end{bmatrix},$$

#### **Matrix Multiplication**







#### Identity Matrix

$$I_{2} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, I_{3} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \dots, I_{n} = \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{bmatrix}.$$

$$2 \times 2 \qquad 3 \times 3 \qquad \qquad n \times n$$
Identiy Matrix Identiy Matrix Identiy Matrix

### The inverse of A is $A^{-1}$ only when:

#### $AA^{-1} = A^{-1}A = \mathbf{I}$



$$\begin{bmatrix} 4 & 7 \\ 2 & 6 \end{bmatrix}^{-1} = \frac{1}{4 \times 6 - 7 \times 2} \begin{bmatrix} 6 & -7 \\ -2 & 4 \end{bmatrix}$$
$$= \frac{1}{10} \begin{bmatrix} 6 & -7 \\ -2 & 4 \end{bmatrix}$$
$$= \begin{bmatrix} 0.6 & -0.7 \\ -0.2 & 0.4 \end{bmatrix}$$

 $\begin{bmatrix} 4 & 7 \\ 2 & 6 \end{bmatrix} \begin{bmatrix} 0.6 & -0.7 \\ -0.2 & 0.4 \end{bmatrix} = \begin{bmatrix} 4 \times 0.6 + 7 \times -0.2 & 4 \times -0.7 + 7 \times 0.4 \\ 2 \times 0.6 + 6 \times -0.2 & 2 \times -0.7 + 6 \times 0.4 \end{bmatrix}$  $= \begin{bmatrix} 2.4 - 1.4 & -2.8 + 2.8 \\ 1.2 - 1.2 & -1.4 + 2.4 \end{bmatrix}$  $= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ So:  $\begin{bmatrix} 4 & 7 \\ 2 & 6 \end{bmatrix}^{-1} = \begin{bmatrix} 0.6 & -0.7 \\ -0.2 & 0.4 \end{bmatrix}$